

# Newtonian Mechanics

## Newton's Law

$$F(t, x(t), \dot{x}(t)) = \ddot{x}(t)$$

## Picard-Lindelöf Thm

$\ddot{x} = G(t, x, \dot{x})$  for  $G$  differentiable, then  $\forall x_0, v_0, \exists T > 0$   
and a unique solution such that  $x(t) : (-T, T) \rightarrow \mathbb{R}$  solves our ODE

### Method one: Taylor series

for analytic  $G$ , use

$$x(t) = \sum_{j=0}^{\infty} \frac{d_j}{j!} t^j \text{ as solution}$$
$$= \underset{x_0}{a_0} + \underset{v_0}{a_1} t + \frac{a_2}{2} t^2 + \frac{a_3}{6} t^3 + \dots$$

### Method two: Euler-Peano iteration

Let  $x(h) \approx x(0) + x'(0)h$

$$x(2h) \approx x(h) + x'(h)h$$

$$x(3h) \approx x(2h) + x'(2h)h$$

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### Method three: Picard iteration

Let  $x_0(t) = x(0)$

$$x_1(t) = x_0(0) + \int_0^t G(s, x_0(s)) ds$$

$$x_2(t) = x_1(0) + \int_0^t G(s, x_1(s)) ds$$

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## Conservation of Energy $F = -V(x)$

Given  $F(x)$ : 1) Calculate  $V(x) = -\int F(x) dx$ ,  $E = \frac{1}{2} \dot{x}^2 + V(x)$

2)  $z(x) = \int_{x_0}^x \frac{1}{\sqrt{2(E_0 - V(x))}} dx'$

3) invert  $z$  to get:  $x(t) = z^{-1}(z \pm t)$

## Equilibrium points An equilibrium point $(x_0, 0) \in \mathbb{R}^2$ satisfies:

$F(x) = 0$  ( $\nabla V(x) = 0$ ) is stable if:  $V''(x_0) > 0$ , is unstable if:  $V''(x_0) < 0$

## Phase portrait Given a potential $V(x)$ , we can plot the phase portrait by:

- Finding all equilibrium points
- Determining their stability

## Conservation of Energy

If  $\exists V \in C^2$  s.t.  $F = -\nabla V$ , then

## Special case of Poincaré Lemma

$\nabla \times F = 0$ , i.e.  $d_j F_i = d_i F_j \quad \forall i, j \Leftrightarrow \exists$  scalar function  $V \in C^2$  s.t.  $F = -\nabla V$

If this holds,  $F$  is conservative, and  $E = \frac{1}{2} \|\dot{x}\|^2 + V(x)$  is conserved

## Bound & Unbound motion

A trajectory  $x: \mathbb{R}_c \rightarrow \mathbb{R}^N$  is bound if  $\exists R > 0$  s.t.  $\|x(t)\| < R \quad \forall t \in \mathbb{R}$   
is unbound otherwise

## Bound motion proposition

Suppose  $F: \mathbb{R}^N \rightarrow \mathbb{R}^N$  conservative, with potential  $V$  s.t.  $\forall \epsilon > 0, \exists R > 0$  s.t.  $|V| < \epsilon \quad \forall x$  s.t.  $\|x\| > R$   
then if  $E_0 < 0$ , the motion is bound

# Lagrangian Mechanics

## Lagrangian

The Lagrangian  $L = T - V$

where  $T$  is the kinetic energy of the system and  $V$  is the potential energy

## Stationary action

$\gamma$  is a stationary point of the action  $\iff$  Euler-Lagrange equations hold:

$$L_x(x, \dot{x}, t) = \frac{d}{dt} L_v(x, \dot{x}, t)$$

## Noether's Theorem

$L \in \mathbb{R}$   $\{T^a: x \mapsto x + a w(x) + O(a^2)\}_{a \in \mathbb{R}}$  be a continuous one parameter family where  $w(x) = \left. \frac{d}{da} T^a(x) \right|_{a=0}$

s.t.  $L(T^a(x), DT^a(x), t) = L(x, v, t)$ , Then  $p := \sum_{i=1}^n L_{v_i} w_i$  is conserved

## Conservation of Hamiltonian

If  $L$  does not depend on time, then the Hamiltonian  $H$  is conserved.

# Hamiltonian Mechanics

## Lagrange Transform

Given Lagrangian  $L$ , for  $p_j = L_{\dot{q}_j}$ ,  $q_j = x_j$  want map  $x \in X(q, p), v(q, p)$ . Note possible if  $L_{\dot{q}_j} \equiv 0 \Rightarrow p_j = 0$

## Hamiltonian

The Hamiltonian  $H(q, p) = \sum_{j=1}^n p_j \dot{q}_j - L(x(q, p), v(q, p))$

## Hamilton's equations

If  $\delta(t) \in \mathbb{E}L$ , then

$q(\delta(t)), p(\delta(t))$  evolve according to:  $\left. \begin{array}{l} \dot{q}_k = \frac{\partial H}{\partial p_k} \\ \dot{p}_k = -\frac{\partial H}{\partial q_k} \end{array} \right\}$

## Hamiltonian Flow

Hamiltonian  $H$  generates a flow in phase space  $\mathbb{R}^{2n}_{x,p}$ , where  $(q, p)$  evolve along an integral curve of the vector field  $\begin{pmatrix} \partial H / \partial p \\ -\partial H / \partial q \end{pmatrix}$

**Liouville's Thm** Let  $\Phi_t: \mathbb{R}^{2n} \rightarrow \mathbb{R}^{2n}$ ,  $(q_0, p_0) \mapsto (q(t), p(t))$

$\Phi_{t+s} = \Phi_s \circ \Phi_t \Rightarrow \Phi_t$  is volume preserving

## Applications in Stat Mech

- $\rho: \mathbb{R}^{2n} \rightarrow \mathbb{R}$  is a density if (i)  $\rho \geq 0$  everywhere (ii)  $\int_{\mathbb{R}^{2n}} \rho(q, p) dq dp = 1$
- $\rho \circ \Phi_t$  is a density
- The flow  $\Phi_t$  generated by a vector field  $V$  is volume preserving  $\iff \nabla \cdot V = 0$

## Poisson brackets

Let  $a(q, p) \in C^\infty(\mathbb{R}^n \times \mathbb{R}^n)$  be an observable, to measure the rate of change in time of  $a$  under evolution of  $H$

$$\{a, H\} = \frac{d}{dt} a(q, p) = \sum_{i=1}^n \partial_{q_i} a \partial_{p_i} H - \partial_{p_i} a \partial_{q_i} H$$

$$\{c_1 f_1 + c_2 f_2, g\} = c_1 \{f_1, g\} + c_2 \{f_2, g\}$$

$$\{f, g\} = -\{g, f\}$$

$$\{f, g\}, h\} + \{f, h\}, g\} + \{g, h\}, f\} = 0$$

Cor: if  $\{f, H\} = 0$ ,  $\{g, H\} = 0$ , then  $\{f, g\}, H\} = 0$

# Formula page

- trig integral
- spherical coordinate
- Symmetry groups